

Chapter 5 Nonlinear Systems

Sect. 5.2 Qualitative Analysis

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Overview

- Question 1) How can we draw the phase portrait of (Detail 1)

$$1) \begin{aligned} \frac{dx}{dt} &= y \\ \frac{dy}{dt} &= x - x^2 \end{aligned}$$

$$2) \begin{aligned} \frac{dy}{dt} &= v \\ \frac{dv}{dt} &= -2x \end{aligned}$$

- Question 2) Did you have a dream as a kid? My dream was

▶ my childish dream

Overview

- 1 Sect. 5.3 Hamiltonian Systems
 - Hamiltonian Systems
 - Examples: The Harmonic Oscillator and the Nonlinear Pendulum
 - Finding Hamiltonian Systems
 - Equilibrium Points of Hamiltonian Systems

Hamiltonian Systems

Conserved Quantity

- A real-valued function $H(x, y)$ of the two variables x and y is a **conserved quantity** for a system of differential equations if it is constant along all solution curves of the system.
- That is if $(x(t), y(t))$ is a solution of the system, then $H(x(t), y(t))$ is constant. In other words,

$$\frac{d}{dt}H(x(t), y(t)) = 0.$$

([PRG], p.494)

Hamiltonian Systems

- Consider

$$\begin{aligned}\frac{dx}{dt} &= y \\ \frac{dy}{dt} &= x - x^2\end{aligned}$$

- Define

$$H(x, y) = \frac{1}{2}y^2 - \frac{1}{2}x^2 + \frac{1}{3}x^3.$$

- For solutions (x, y) ,

$$\frac{d}{dt}H(x(t), y(t)) = 0. \quad (\text{Detail 2})$$

- The solution curves always lie along the level curves of H .

Hamiltonian Systems

The Level curves of H .

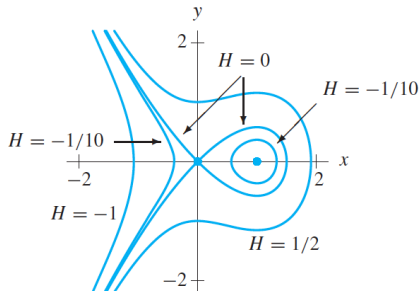


Figure 5.25

Now we can draw phase portrait. (Detail 3)

The phase portrait

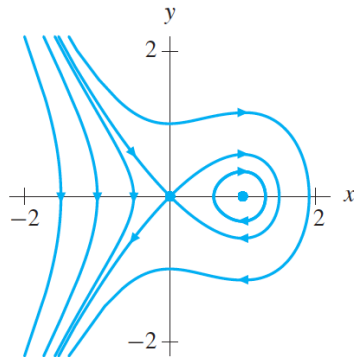


Figure 5.24

Hamiltonian Systems

Definition

- A system of differential equations is called a **Hamiltonian system** if there exists a real-valued function $H(x, y)$ such that

$$\begin{aligned}\frac{dx}{dt} &= \frac{\partial H}{\partial y} \\ \frac{dy}{dt} &= -\frac{\partial H}{\partial x}\end{aligned}$$

for all x, y .

- The function H is called the **Hamiltonian function** for the system.

Hamiltonian System

- Note H is always a conserved quantity for such a system.
(Detail 4)
- Sketching the phase portrait for a Hamiltonian system is the same as sketching the level sets of the Hamiltonian function.

Examples: The Harmonic Oscillator

- Recall that the undamped harmonic oscillator system is

$$\begin{aligned}\frac{dy}{dt} &= v \\ \frac{dv}{dt} &= -qy\end{aligned}$$

where q is a positive constant.

- Let

$$H(y, v) = \frac{1}{2}v^2 + \frac{q}{2}y^2.$$

- Then

$$\frac{dy}{dt} = \frac{\partial H}{\partial v}, \quad \frac{dv}{dt} = -\frac{\partial H}{\partial y}.$$

- Hence the undamped harmonic oscillator is a Hamiltonian system.

Examples: The Harmonic Oscillator

- Going back to the first question

$$\begin{aligned}\frac{dy}{dt} &= v \\ \frac{dv}{dt} &= -2x,\end{aligned}$$

a Hamiltonian function is

$$H(y, v) = \frac{1}{2}v^2 + y^2.$$

- Therefore, the solution curves are ellipses.

The Nonlinear Pendulum

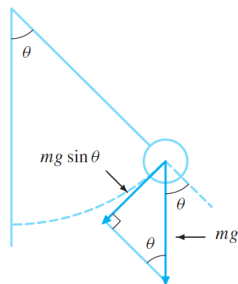
Consider a pendulum.



Figure 5.27
A pendulum with
rod length l and
angle θ .

([PRG], p.495)

We assume there are only two
forces: gravity and friction.



The Nonlinear Pendulum

- Using Newton's second law,

$$-bl \frac{d\theta}{dt} - mg \sin \theta = ml \frac{d^2\theta}{dt^2}$$

where b is the coefficient of damping,

- which is often written as

$$\frac{d^2\theta}{dt^2} + \frac{b}{m} \frac{d\theta}{dt} + \frac{g}{l} \sin \theta = 0.$$

- Suppose $b = 0$ and $l = 1$.

The Nonlinear Pendulum

We rewrite the equation as a first-order system in the usual manner to get

$$\begin{aligned}\frac{d\theta}{dt} &= v \\ \frac{dv}{dt} &= -g \sin \theta.\end{aligned}$$

- Find equilibrium points: $(n\pi, 0)$ where n is any integer.
- Let

$$H(\theta, v) = \frac{1}{2}v^2 - g \cos \theta.$$

-

The Nonlinear Pendulum

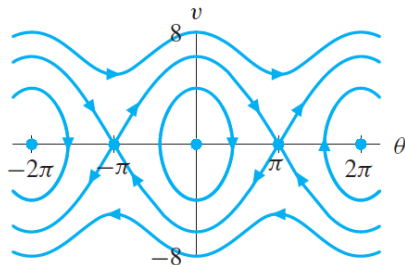


Figure 5.30

Phase portrait for the ideal pendulum.

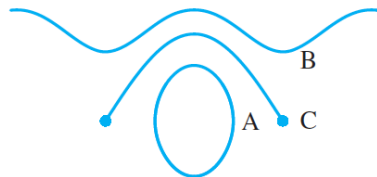


Figure 5.31

Special solution curves.

▶ my childish dream

Finding Hamiltonian Systems

Study how to determine if a given system is a Hamiltonian system.

- Consider

$$\begin{aligned}\frac{dx}{dt} &= f(x, y) \\ \frac{dy}{dt} &= g(x, y).\end{aligned}$$

- If the system is Hamiltonian,

$$\frac{\partial f}{\partial x} = -\frac{\partial g}{\partial y} \quad (\text{Detail 5})$$

- The converse is also true.

([PRG], p.498)

Finding Hamiltonian Systems

- Examples (Detail 6)

$$\begin{array}{lll}
 1) \frac{dx}{dt} = x + y^2 & 2) \frac{dx}{dt} = y & 3) \frac{dx}{dt} = -x \sin y + 2y \\
 \frac{dy}{dt} = y^2 - x & \frac{dy}{dt} = x - x^2 & \frac{dy}{dt} = -\cos y.
 \end{array}$$

- # 14

Show the system

$$\begin{aligned}
 \frac{dx}{dt} &= F(y) \\
 \frac{dy}{dt} &= G(x).
 \end{aligned}$$

is Hamiltonian.

Finding Hamiltonian Systems

Review Exercise for Chapter 5

28

Consider the linear system

$$\frac{d\mathbf{Y}}{dt} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mathbf{Y}.$$

For which values of a , b , c , and d is the system Hamiltonian?

Equilibrium Points of Hamiltonian Systems

Hamiltonian systems have a number of special properties not shared by general systems.

Question) Can you tell which one is Hamiltonian?

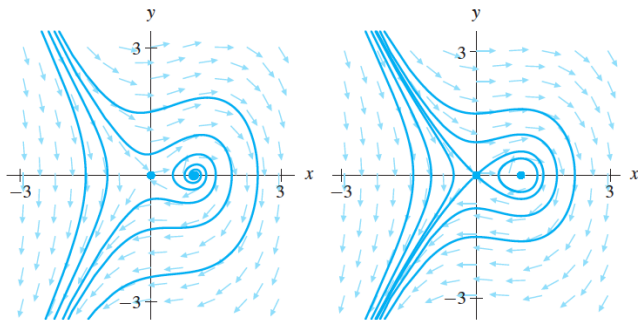


Figure 5.33

Equilibrium Points of Hamiltonian Systems

- For a Hamiltonian system, the Jacobian matrix assumes the form

$$\begin{pmatrix} \alpha & \beta \\ \gamma & -\alpha \end{pmatrix}. \quad (\text{Detail 7})$$

- Thus there are only three possibilities: (Detail 8)
 - 1 The equilibrium point is a saddle
 - 2 The equilibrium point is a center.
 - 3 The only eigenvalue is 0.

([PRG], p.502)

Equilibrium Points of Hamiltonian Systems

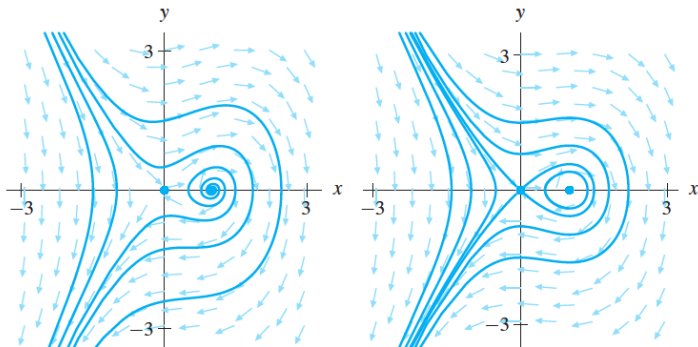


Figure 5.33

The phase portrait on the left cannot be a Hamiltonian system, whereas the phase portrait on the right might be Hamiltonian.

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What's next: Sect. 5.4 Dissipative Systems

Homework

- Suggested Exercises (optional): 1, 9, 11, 13, 14, 15, 17
- Homework Exercises (required to submit): 1, 9, 11, 17

References



Paul Blanchard, Robert L. Devaney, Glen R. Hall
Differential Equations, fourth edition.